

# KX Series

## Digital temperature controller

- Multi input
- Position of the decimal point selection
- 2 stage step function by the external contact (KX4S)
- Select the output action : reverse action/direct action
- PID auto tuning
- Control Loop Break Alarm (LBA)
- Absolute / deviation alarm (high, low, within range)
- Input compensation setting



### ● Suffix code

| Model                               |    | Code    | Description                                      |                                  |
|-------------------------------------|----|---------|--|----------------------------------|
| KX                                  | □- | □ □ □ □ | Digital Temperature Controller                   |                                  |
|                                     | 2N |         | 48(W) X 96(H) mm                                 |                                  |
|                                     | 3N |         | 96(W) X 48(H) mm                                 |                                  |
|                                     | 4N |         | 48(W) X 48(H) mm                                 |                                  |
|                                     | 7N |         | 72(W) X 72(H) mm                                 |                                  |
|                                     | 9N |         | 96(W) X 96(H) mm                                 |                                  |
| Dimension                           | 4S |         | 48(W) X 48(H) mm                                 | for 11 pin socket                |
|                                     | M  |         | Relay  |                                  |
|                                     | S  |         | SSR (voltage pulse 12 V DC)                      |                                  |
|                                     | C  |         | SCR (Current 4 – 20 mA DC)                       |                                  |
| Control output                      | C  |         | ※ KX4N, KX4S selection only                      | ALH, ALL, LBA (1a common output) |
|                                     | E  |         | ※ KX4S selection inhibited                       |                                  |
|                                     |    |         | KX2N, KX3N, KX9N                                 | ALH (1c), ALL(1a)                |
|                                     |    |         | KX7N, KX4N (optional)                            | ALH (1a), ALL(1a)                |
|                                     | K  |         | ※ KX4N, KX4S selection inhibited                 |                                  |
|                                     |    |         | KX2N, KX3N, KX9N (optional)                      | ALH (1c), ALL(1a), LBA(1a)       |
|                                     |    |         | KX7N (optional)                                  | ALH (1a), ALL(1a), LBA(1a)       |
| Retransmission output<br>(Optional) | A  |         | ※ Only selectable with models given in the below |                                  |
|                                     |    |         | KX4N-□C  | Retransmission output(RET)       |
|                                     |    |         | KX2N-□E, KX3N-□E, KX9N-□E                        | 4 – 20 mA DC                     |
|                                     |    |         | KX2N-□K, KX3N-□K, KX9N-□K                        |                                  |
| Power Supply Voltage                | N  |         | None   |                                  |
|                                     | A  |         | 100 – 240 V AC, 50 – 60 Hz                       |                                  |
|                                     | D  |         | 24 V DC (KX4S selection inhibited)               |                                  |

\* When using 4–20 mA input, attach 0.1 % of 250 Ω resistance to the input terminal of 1 – 5 V DC

## ● Specification

### Input

|                                    |  |
|------------------------------------|--|
| Thermocouple                       | K, J, E, T, R, B, S, L, N, U, W, PL2                                 |
| RTD input                          | Pt 100 Ω, KPt 100 Ω  |
| DC rated voltage                   | 1 – 5 V DC ( 4 – 20 mA DC), 0 – 10 V DC                              |
| Input display resolution           | Usually less than the decimal points of range                        |
| Input sampling time                | 250 ms   |
| Allowable signal source resistance | Max. 250 Ω (Thermocouple input), max. 2 KΩ(DC voltage input)         |
| Allowable wiring resistance        | RTD : max 10Ω /1 wire, however resistance among 3 wires must be same |
| Allowable input voltage            | Within ±20 V for 1 min   |
| Scaling                            | 0.0 % ~ 100.0 % of FS  |
| Cold junction compensation error   | ±3.5 °C (0 ~ 50 °C)  |
| Input break function               | With the input break, up-scale and output become OFF                 |

### Performance

|                       |  |
|-----------------------|--|
| Display accuracy      | ±0.5 % of FS<br>but, range 0 ~ 400 of B thermocouple are excluded from the guaranteed range. |
| Insulation resistance | Min 20 MΩ, 500 V DC, for 1 min (between the 1st and 2nd terminal)                            |
| Dielectric strength   | 2,300 V AC, 50 / 60 Hz, for 1 min (between the 1st and 2nd terminal)                         |

### Control function and output

|                                     |   |
|-------------------------------------|---|
| Range setting                       | Please refer to the range and input code  |
| Control type                        | PID control, ON/OFF control   |
| Proportional band(P)                | Within the input range  |
| Integral time                       | 0 ~ 3600 sec  |
| Differential time                   | 0 ~ 3600 sec  |
| Anti reset wind up (A.R.W)          | Within the input range  |
| Control loop break alarm (LBA)      | 0 ~ 7200 sec  |
| Proportional cycle                  | 0 ~ 100 sec   |
| Control output hysteresis           | 0 ~ 10 % of FS  |
| ON/OFF control                      | Set the proportional band to "0" (0.0)  |
| Alarm type                          | Absolute alarm, deviation alarm (high alarm, low alarm, within range alarm)           |
| Indication when range exceeded      | Exceeding max range "0000" flickers, exceeding min range "UUUU" flickers              |
| Decimal point function              | With DC rated voltage, select the position of decimal point which caused by parameter |
| Position of decimal point selection | DC voltage, select the decimal point with current input (0~3 digits)                  |
| Input compensation value setting    | -100.0 ~ 100.0 of FS  |
| High or low alarm hysteresis        | 0 ~ 10 % of FS  |
| High/Low range limitation           | Within the input range  |
| Output action                       | Direct action/reverse action (selected by parameter)                                  |
| Scaling setting                     | -199 ~ 9999 (high and low scaling setting when inputting DC voltage)                  |

## ● Output

|                       |         |  |
|-----------------------|---------|--|
| Control output        | Relay   | NO : 5 A 250 V AC, 5 A 30 V DC (resistive load)<br>NC : 3 A 250 V AC, 1 A 30 V DC (resistive load)                                       |
|                       | SSR     | 12 V DC min, pulse voltage (load resistance min 600 Ω)   |
|                       | SCR     | 4 – 20 mA DC (load resistance max 600 Ω), accuracy : ±0.2 mA   |
| Alarm output          | Relay   | 250 V AC 3 A (load resistance) *please refer to the connection diagram (contact) just, KX4N : 1a contact, 250 V AC 1 A (load resistance) |
| Retransmission output | Current | 4 – 20 mA DC (load resistance max 600 Ω), accuracy : ±0.2 mA   |

## General specification

| Model                               | KX2N   | KX3N          | KX4N          | KX4S          | KX7N          | KX9N          |  |  |  |  |
|-------------------------------------|--|---------------|---------------|---------------|---------------|---------------|--|--|--|--|
| Power Supply Voltage                | 100 – 240 V AC, 50 – 60 Hz, 24 V DC (KX4S selection inhibited) |               |               |               |               |               |  |  |  |  |
| Voltage fluctuation                 | ±10 % of the Power Supply Voltage                              |               |               |               |               |               |  |  |  |  |
| Power consumption                   | 11 VA max.   |               | 7 VA max.     |               | 11 VA max.    |               |  |  |  |  |
| Ambient Temperature                 | 0 ~ 50 °C  |               |               |               |               |               |  |  |  |  |
| Ambient humidity                    | 35 ~ 85 % RH (without dew condensation)                        |               |               |               |               |               |  |  |  |  |
| Vibration Resistance                | 10 – 55 Hz, 0.76 mm, 2 hrs each in X, Y and Z direction        |               |               |               |               |               |  |  |  |  |
| Shock Resistance                    | 300 m/s <sup>2</sup> to the direction 6 each 3 times           |               |               |               |               |               |  |  |  |  |
| Weight (included the weight of box) | approx. 320 g  | approx. 320 g | approx. 180 g | approx. 180 g | approx. 300 g | approx. 400 g |  |  |  |  |

## Range and input code

| Classification                | code<br>(SL1) | Input signal         | Range(°C)         |                                |
|-------------------------------|---------------|----------------------|-------------------|--------------------------------|
|                               |               |                      | 1 °C (SL2 : X1XX) | 0.1 °C (SL2 : X0XX)            |
| Thermocouple                  | 0001          | K                    | -50 ~ 1300        | -50.0 ~ 999.9                  |
|                               | 0101          | J *2                 | -50 ~ 600         | -50.0 ~ 600.0                  |
|                               | 1100          | E                    | -199 ~ 999        | -199.9 ~ 999.9                 |
|                               | 1101          | T                    | -50 ~ 400         | -50.0 ~ 400.0                  |
|                               | 0100          | R                    | 0 ~ 1700          | 0.0 ~ 999.9                    |
|                               | 0110          | B *1                 | 0 ~ 1800          | 0.0 ~ 999.9                    |
|                               | 0111          | S                    | 0 ~ 1700          | 0.0 ~ 999.9                    |
|                               | 1000          | L *2                 | -199 ~ 900        | -199.9 ~ 900.0                 |
|                               | 1001          | N *2                 | -199 ~ 1300       | -199.9 ~ 999.9                 |
|                               | 1010          | U                    | -50 ~ 400         | -50.0 ~ 400.0                  |
|                               | 1011          | W (Re5-Re25)         | 0 ~ 2300          | 0.0 ~ 999.9                    |
|                               | 1110          | PL2                  | 0 ~ 1300          | 0.0 ~ 999.9                    |
| RTD                           | 0010          | KPt100 Ω (old model) | -199 ~ 500        | -199.9 ~ 500.0                 |
|                               | 0011          | Pt100 Ω (IEC)        | -199 ~ 640        | -199.9 ~ 640.0                 |
| DC Voltage<br>Voltage Current | 0000          | 1 – 5 V DC *3        | -199 ~ 9999       | Decimal point selection by SL4 |
|                               | 1111          | 0 – 10 V DC *3       |                   |                                |

\* When using 4-20 mA input, attach 0.1 % of 250 Ω shunt resistance at the both ends of the input terminal within 1 – 5 V DC input mode

\* Accuracy : ±0.5 % of FS

\*1 : range 0 ~ 400 °C are excluded from the guaranteed range

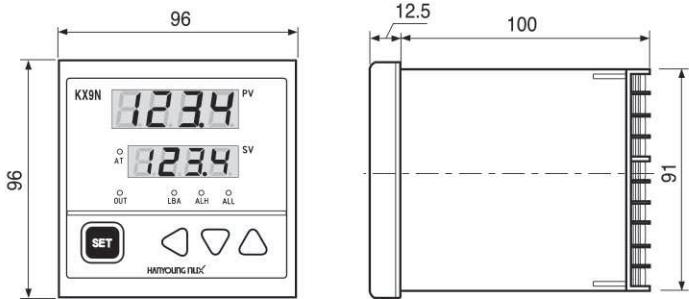
\*2 : range with less than 0 °C, ±1 % of FS      \*3 : ±1 % of FS

**A**

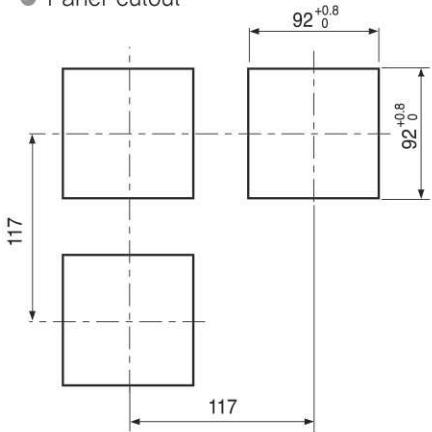
● Dimension and panel cutout (unit : mm)

**KX9N**

● Dimension

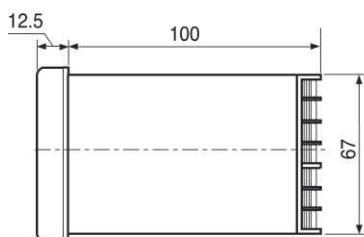
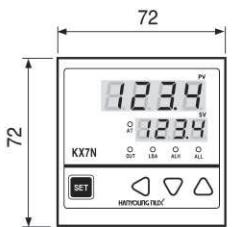


● Panel cutout

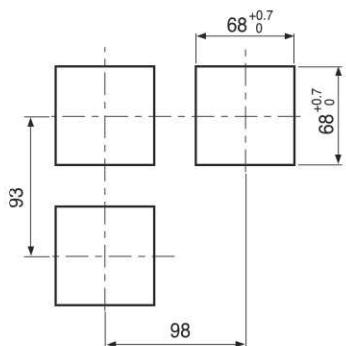


**KX7N**

● Dimension



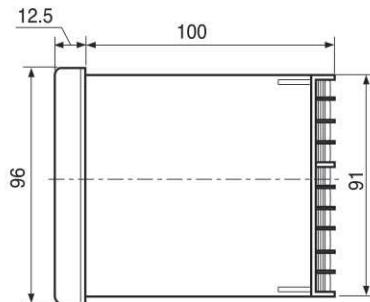
● Panel cutout



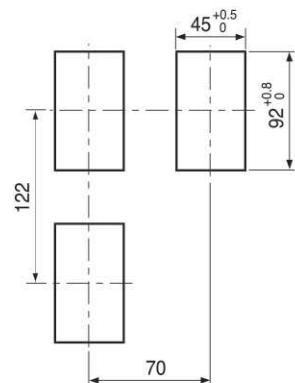
A

## KX2N

## ● Dimension

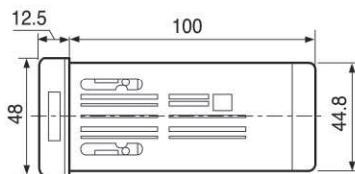


## ● Panel cutout

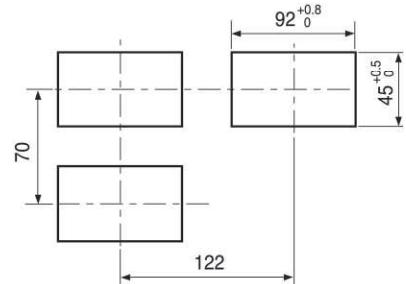


## KX3N

## ● Dimension

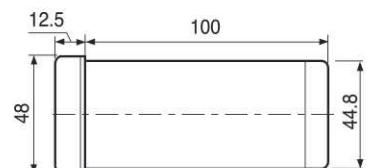


## ● Panel cutout

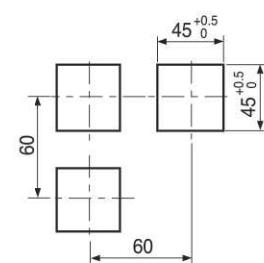


## KX4N

## ● Dimension

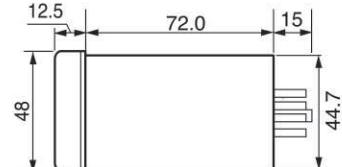


## ● Panel cutout

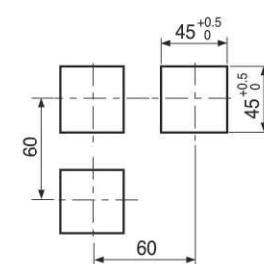


## KX4S

## ● Dimension

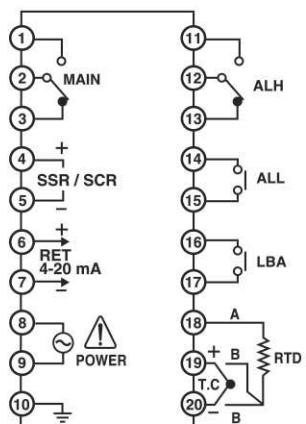


## ● Panel cutout

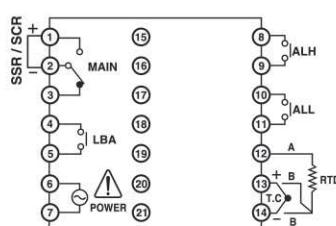


## ● Connection diagram

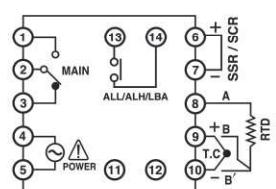
### ● KX 2N / 3N / 9N



### ● KX 7N



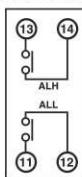
### ● KX 4N



• Standard(C)

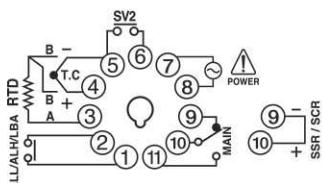


• alarm 2 contact (E)



• Standard(C) + Retransmission output(A)

### ● KX 4S



## ● Main function explanation

### ■ Auto tuning (AT)function

Auto tuning function measures, computes and sets the optimum PID or ARW constant to the temperature control automatically.

After supplying power in and while temperature is increasing, press the **SET** key and **△** key synchronously to begin the auto tuning. When auto tuning is finished, tuning operation will be ended automatically.

### ■ LBA : Control Loop Break Alarm

LBA function starts to measure time from the moment when the PID computed value becomes 0 % or 100 %. Also, from this point, this function detects heater break, sensor break, manipulator malfunction and etc by comparing the changed amount of measured value in each set time. Also, it can set the LBA dead band in order to prevent any malfunction to happen in the normal control loop.

- ① When control output value which obtained by PID operation is 100 %, LBA will be ON only when process value does not rise more than 2 °C in the LBA setting time
- ② When control output value which obtained by PID operation is 0 %, LBA will be ON only when process value does not drop more than 2 °C in the LBA setting time

### ■ Heating/Cooling output action selection

Able to select reverse action (heating control) or direct action (cooling control) output by the internal parameter

① Reverse action: ON with measurement value < Setting value

② Direct action: ON with measurement > Setting value

### ■ ON/OFF control setting method

Usually temperature controller performs the temperature control by "PID control method" which is by the PID auto-tuning. However, ON/OFF control method is used when controlling refrigerator, fan, solenoid valve and etc. When users want to set the temperature controller as ON/OFF control mode, set the set value of proportional band as 0 in the "general setting parameter". Here, HYS (hysteresis) parameter will be displayed. Prevent such actions by setting the desired ON/OFF action range.

| Parameter symbol | Name   | Set range | Default value |
|------------------|--|-----------|---------------|
| P                | Proportional band  | 0 ~ 100 % | 20 °C         |
|                  | Set the proportional band as "0" when using ON/OFF control. However, performing PID auto-tuning when using the ON/OFF control, it will be changed to PID control |           |               |

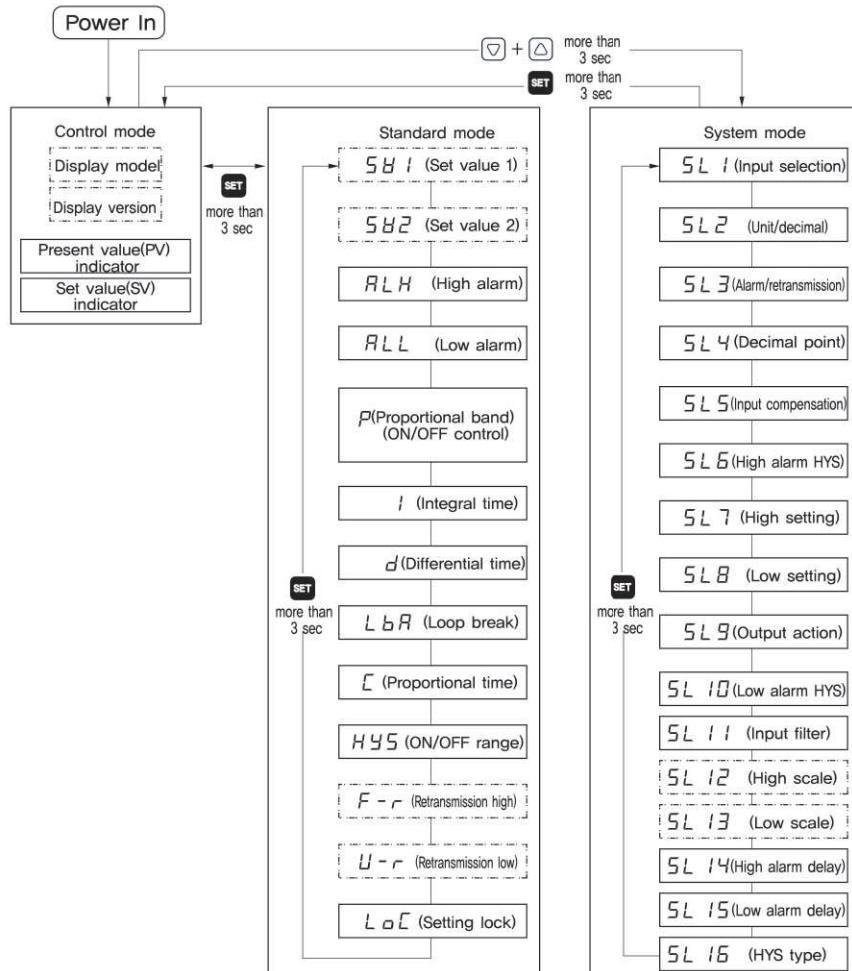
### ■ 2 stage step function by external contact (Only with model KX4S)

It can select 2 types of control target value that has been set in advance by external contact input ON/OFF so it can be applied to the step control and etc easily. (SV1 selection = #5 – #6 OFF)

### ■ Max range and min range exceeded indication

- ① If the present value increases due to the input break (sensor break) or etc and exceeds the maximum temperature range then **00000** (indication of exceeding the max range) will flicker in the measured value displaying unit.
- ② If present value decreases and exceeds the minimum temperature range then **LILIL** (indication of exceeding the min range) will flicker in the measured value displaying unit.

### Parameter composition



**Parameter setting****■ Control temperature setting**

Supplying the power in after completes the wiring, it will display the model and version of temperature controller for a while and display measured temperature and set temperature. This state is called as control mode.

Pressing the **SET** key in the control mode state will flicker the set value in the indicator.

**■ General mode setting**

General mode is the setting mode which sets alarm set value, ON/OFF action, hysteresis (HYS) and etc which are required to change the set value frequently. It sets each parameter when necessary.

But, performing the PID auto-tuning will automatically set **P**(proportional band), **I** (integral time), **D**(differential time), **A** (anti reset wind up), **LBA**(control loop break alarm) and etc

\*(Press the **MODE** key for 3 seconds continuously.)

| Present value display unit             | Name       | Default value              | Setting range | Explanation        |  |
|--|------------|----------------------------|---------------|--------------------|--|
| *1<br>*1<br>*1<br>*1<br>*1<br>*2<br>*2 | <b>SV1</b> | Set value 1                | -50 °C        | within input range | Set value 1 (SV 1)   |
|  | <b>SV2</b> | Set value2                 | -50 °C        |                    | Set value 2 (SV 2)   |
|  | <b>ALH</b> | High alarm                 | 1,300 °C      |                    | display the set value of high alarm.   |
|  | <b>ALL</b> | Low alarm                  | -50 °C        |                    | display the set value of low alarm.  |
|  | <b>P</b>   | Proportional band          | 20 °C         | 0~100% of FS       | set when performing the proportional control. Setting to '0' will be as ON/OFF control.  |
|  | <b>A</b>   | Anti reset wind up         | 20 °C         | 0~100% of FS       | prevents overshoot and undershoot caused by integral effectiveness. Automatically operates with setting '0'.                               |
|  | <b>I</b>   | Integral time              | 240sec        | 0~3600sec          | Eliminates offset occurring in proportional control, and reach faster Integral action will be turned OFF with setting '0'.                 |
|  | <b>D</b>   | Differential time          | 60sec         | 0~3600sec          | prevents ripples by predicting output change thereby improving control stability. Differential action will be turned OFF with setting '0'. |
|  | <b>LBA</b> | Control loop break alarm   | 0sec          | 0~7200sec          | Indicates control loop break alarm setting. Not operated with [0]setting   |
|  | <b>C</b>   | Proportional cycle         | *3            | 1~100sec           | Displays control output cycle (sec).   |
| *2<br>*2                               | <b>HYS</b> | Hysteresis                 | 1 °C          | 0~10 % of FS       | set the control sensitivity of control output (main output)(with ON/OFF)   |
|  | <b>F-r</b> | High Retransmission output | 1,300 °C      | within input range | limits the max value of Retransmission output  |
|  | <b>U-r</b> | Low Retransmission output  | -50 °C        |                    | limits the min value of Retransmission output.   |
|  | <b>Loc</b> | Set data lock              | 0000          | 0000~0003          | Set the set data lock level  |

\* 1 is exclusive for KX4S specification (Not displayed with other specifications)

\* 2 is optional (If the model does not have retransmission output then not displayed)

\* 3 varies the default value depending on the control input

(20 sec with relay output, SSR output : 2 sec)

## System mode setting

The system mode sets the specification of temperature controller in the first installation by engineer

In the control mode press and keys at the same time for 3 seconds to enter in to the initial setting mode

Press the key or 3 seconds to return to the operation mode (PV/SV)

A

Temperature Controller

→ (Press the key.)

| Symbol (PV display screen) | List  | Description  | Default value (SV display screen) |
|----------------------------|---|--|-----------------------------------|
| <b>SL1</b>                 | Input selection   | Multi input, "Please refer to the range and input code"  | 0001<br>(K Thermocouple)          |
| <b>SL2</b><br>             | ① Output selection<br>② Decimal point function selection<br>③ Temperature unit selection<br>④ Indicator/controller selection              | 0 : Current output<br>1 : Relay, voltage output<br>0 : Without decimal point<br>1 : With decimal point<br>0 : None<br>1 : Celsius(°C)<br>0 : Temperature indicator<br>1 : Temperature controller | 1111                              |
| <b>SL3</b><br>             | ① Alarm standby action selection<br>② Retransmission output (optional):<br>③ Alarm type selection<br>④ Deviation/absolute alarm selection | 0 : With standby operation<br>1 : NONE<br>0 : With the Retransmission output<br>1 : NONE<br>0 : Alarm within the range<br>1 : High and low alarm<br>0 : Deviation alarm<br>1 : Absolute alarm    | 1111                              |
| <b>SL4</b>                 | Position of decimal point selection   | 0 → 0000 (none) 1 → 000.0 (1 <sup>st</sup> )<br>2 → 00.00 (2 <sup>nd</sup> digit) 3 → 0.000 (3 <sup>rd</sup> digit)  | 0                                 |
| <b>SL5</b>                 | Input compensation value setting  | ±100 % of FS   | 0                                 |
| <b>SL6</b>                 | High alarm(ALH) hysteresis setting  | ± 10% of max range   | 1                                 |
| <b>SL7</b>                 | Max temperature setting   | Within temperature setting but, SL7 > SL8  | 1300                              |
| <b>SL8</b>                 | min temperature setting   |  | -50                               |
| <b>SL9</b>                 | Control output action   | 0: Reverse action (heating)<br>1 : Direct action (cooling)   | 0                                 |
| <b>SL10</b>                | Low alarm hysteresis setting  | ±10 % of max range   | 1 °C                              |
| <b>SL11</b>                | Input filter  | 0 ~ 100 sec  | 0                                 |
| <b>SL12</b>                | Max input scale setting   | 9999   | 9999                              |
| <b>SL13</b>                | Min input scale setting   | -1999  | -1999                             |
| <b>SL14</b>                | High alarm (ALH) delay time setting   | 0 ~ 100sec   | 0 sec                             |
| <b>SL15</b>                | Low alarm (ALL) delay time setting  | 0 ~ 100sec   | 0 sec                             |
| <b>SL16</b>                | Control output hysteresis type selection  | 0: Hysteresis<br>1 : Hysteresis X double action (left, right)  | 0                                 |